

PSEUDO-EINSTEIN AND Q-FLAT METRICS WITH EIGENVALUE ESTIMATES ON CR-HYPERSURFACES

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ABSTRACT.

In this paper, we will use the Kohn's $\bar{\partial}_b$ -theory on CR-hypersurfaces to derive some new results in CR-geometry.

Main Theorem. *Let M^{2n-1} be the smooth boundary of a bounded strongly pseudoconvex domain Ω in a complete Stein manifold V^{2n} . Then (1) For $n \geq 3$, M^{2n-1} admits a pseudo-Einstein metric; (2) For $n \geq 2$, M^{2n-1} admits a Fefferman metric of zero CR Q -curvature; and (3) for a compact strictly pseudoconvex CR emendable 3-manifold M^3 , its CR Paneitz operator P is a closed operator.*

There are examples of non-emendable strongly pseudoconvex CR manifold M^3 , for which the corresponding $\bar{\partial}_b$ -operator and Paneitz operators are not closed operators.

0. INTRODUCTION

In this paper, we study several questions, including the existence of Q -flat metrics, pseudo-Einstein metrics and the closedness of the CR Paneitz operators.

First, we will use an approach proposed by Fefferman and his school to prove that “the complete Kähler-Einstein g_∞ on an open domain Ω induces a metric on $M = b\Omega$ with zero CR Q -curvature, where Ω is a smooth, bounded strictly pseudoconvex domain in a Stein manifold V^{2n} .” To achieve this goal, we solve a $\partial\bar{\partial}$ -Poincaré-LeLong equation via the $\bar{\partial}$ -theory. Although this part does not produce new hard a-priori estimates, it is still valuable for other potential applications.

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The second purpose is to prove the existence of pseudo-Einstein metrics on strictly pseudo-convex CR -hypersurface of real dimension ≥ 5 through solving the $\bar{\partial}_b$ Poincaré-LeLong equations.

The last part of our paper is to study the closedness of CR Paneitz operator, which is a fourth-order differential operator. It is known that the positivity of CR Paneitz operator is related to the deformation of Q -curvatures under the conformal change of metrics on Riemannian manifold M^m . In particular, the positivity of CR Paneitz operator is also related to the lower bound of the first eigenvalue of sub-Laplace on a CR manifold M^3 , see [CC], [CCC] and [LL]. It will be shown that, if $M^3 = b\Omega^4$ is the smooth boundary of bounded strictly pseudo-convex domain Ω in a Stein manifold V^4 , then its CR-Paneitz operator on M^3 is closed, for any metric on M^3 .

Main Theorem. *Let M^{2n-1} be the smooth boundary of a bounded strongly pseudo-convex domain Ω in a complete Stein manifold V^{2n} . Then*

- (1) *For $n \geq 2$, M^{2n-1} admits a metric of zero CR Q -curvature;*
- (2) *For $n \geq 3$, M^{2n-1} admits a pseudo-Einstein metric;*
- (3) *In addition, for a compact strictly pseudoconvex CR emendable 3-manifold M^3 , its CR Paneitz operator P is a closed operator.*

Earlier work in this direction for the case of $V^{2n} = \mathbb{C}^n$ can be found in [L2], [FH] and [GG]. In a very recent paper [LL], Li and Luk obtained an explicit formula for Webster's pseudo-Ricci curvature on real hypersurfaces in \mathbb{C}^n . Thus, their result could lead another proof of Cheng-Yau's result ([CY]) and Mok-Yau's theorem [MY], which will be used in Section 2 below.

Among other things, we introduce some new methods to handle pseudo-Einstein metric and Paneitz operators in this paper. For example, we use the closeness of $\bar{\partial}_b$ and $\bar{\partial}_b^*$ operators provided by Kohn's theory, in order to complete the proof. When $\dim_{\mathbb{R}}[M] = 3$, we decompose the Paneitz operator P as a product of closed

operators. Thus, the closed property of P will follow immediately, see Lemma 1.4 and Section 4 below.

1. PRELIMINARY RESULTS

It is well-known that the real Laplace Δ on a Kähler manifold V^{2n} satisfies

$$\Delta = 2\Box = 2\bar{\Box},$$

where $\Box = \bar{\partial}\bar{\partial}^* + \bar{\partial}^*\bar{\partial}$ is the complex Laplace operator. However, it may happen that $\Delta_b \neq 2\Box_b$ in some cases. Let us recall the notions of Δ_b and \Box_b .

Since $M^{2n-1} = bV^{2n}$ has odd real dimension, it is a Cauchy-Riemann manifold. The $\bar{\partial}_b$ operator induces a sub-elliptic operator

$$\Box_b = \bar{\partial}_b^* \bar{\partial}_b + \bar{\partial}_b \bar{\partial}_b^*$$

acting on $L^2_{(p,q)}(M)$. Similarly, there is a real sub-Laplace operator, which can be viewed as partial trace of the hessian operator (or can be viewed a sum of the squares of $(2n-2)$ vectors):

$$\Delta_b u|_z = \sum_{k=1}^{2n-2} \langle \nabla_{e_k}(\nabla^b u), e_k \rangle|_z$$

where e_{2n} is the outward real unit normal vector of Ω along boundary $M = b\Omega$, $e_{2j} = J e_{2j-1}$ for $j = 1, \dots, n$, $z \in M$, J is the complex structure of V^{2n} , $\{e_1, e_2, \dots, e_{2n-3}, e_{2n-2}, e_{2n-1}, e_{2n}\}$ is an orthonormal basis of $[T_z(V)]_{\mathbb{R}}$ and

$$\nabla^b u = \sum_{k=1}^{2n-2} du(e_k) e_k.$$

When Ω has the strongly pseudo-convex boundary in a Stein manifold V^{2n} with $n = 2$, it has been observed that

$$\Box_b u = \frac{1}{2}[\Delta_b u + \sqrt{-1}Tu] \tag{1.1}$$

for all $u \in L^2(M^3)$, where $T = \lambda e_3$ is the Reeb vector of the CR 3-manifold M^3 for some real valued function λ , see [L1, p414].

The operator \square_b is a Lewy type operator, which may *not* be locally solvable.

If the Reeb vector T induces an infinitesimal pseudo-conformal with respect to the Tanaka-Webster metric, then the torsion of M^3 is zero, see [Web, p33]. In this case, the operator \square_b is related to the so-called CR Paneitz operator P , where P is given by

$$Pu = \Delta_b^2 u + T^2 u = 4\square_b \bar{\square}_b u, \quad (1.2)$$

for $u \in L^2(M^3)$. More generally, if M^3 has torsion free in the sense of Tanaka (cf. [Ta1-2] [Web]), then (1.2) holds.

The eigenvalues of the Paneitz operator and CR Paneitz operators have been considered various authors ([Ch], [CC]). The eigenvalue estimate plays an important role to the study of the so-called Q-curvature flow, see [Br] [CCC].

Definition 1.1. (1) *The CR-Paneitz operator $P : L^2(M^3) \rightarrow L^2(M^3)$ is called essentially positive, if there is a positive constant $\lambda_1 > 0$ such that*

$$\langle Pu, u \rangle \geq \lambda_1 \|u\|^2, \quad (1.3)$$

for all $u \perp \ker(P)$.

(2) *The operator $\mathcal{F} : L_{(p,q)}^2(M) \rightarrow L_{(p,q)}^2(M)$ is said to have positive spectrum gap at 0 (or is said to be a closed operator) if there is a positive constant $\lambda_{p,q} > 0$ such that*

$$\|\mathcal{F}u\| \geq \lambda_{p,q} \|u\|, \quad (1.4)$$

for all $u \perp [L_{(p,q)}^2(M) \cap \ker(\mathcal{F})]$.

(3) *A smooth function $f : U_\varepsilon(M) \rightarrow \mathbb{R}$ is called a defining function of M if $f^{-1}(0) = M$ and if 0 is not a critical value of f , where $U_\varepsilon(M) \subsetneq V^{2n}$ is a neighborhood of M in a Stein manifold V^{2n} .*

(4) *Let θ be a contact 1-form of M^{2n-1} and $J : \ker \theta \rightarrow \ker \theta$ be the almost complex structure on the CR-distribution $\ker \theta$ such that $J^2 \vec{v} = -\vec{v}$ for all $\vec{v} \in \ker \theta$.*

In what follows, we always let

$$[T^{(1,0)}(M) \oplus T^{(0,1)}(M)] = [\ker \theta] \bigotimes_{\mathbb{R}} \mathbb{C}.$$

(5) A CR manifold M^{2n-1} is said to have transverse symmetry or torsion-free if it admits a CR Reeb vector field ξ such that $\xi \notin \ker \theta$ with

$$\mathcal{L}_\xi J = 0$$

where \mathcal{L} is the Lie derivative and J is the complex structure of $[T^{(1,0)}(M) \oplus T^{(0,1)}(M)]$.

If ξ is the real part of a holomorphic vector field \tilde{X} on a neighborhood $U_\varepsilon(M)$ of M , then ξ induces an automorphism on $U_\varepsilon(M)$. Any real part ξ of a holomorphic vector field restricted to M induces a CR-automorphism of M .

In the Hörmand-Kohn L^2 -theory and the Kohn-Rossi theory, the essential spectrum of \square and \square_b have been extensively investigated.

A smooth (p, q) -form u on Ω with $q \geq 1$ is said to satisfy the $\bar{\partial}$ -Neumann boundary condition if

$$u((\bar{\partial}\rho)_\#, \dots)|_z = 0$$

for all $z \in M = b\Omega$, where $(\bar{\partial}\rho)_\#$ is the complex normal vector field of type $(0, 1)$ along the boundary M^{2n-1} .

Theorem 1.2. ([CS], [CaWS]) Let Ω be a bounded domain with smooth pseudoconvex boundary M in a complete Hermitian manifold V^{2n} . Suppose that V^{2n} is either a Stein manifold or $\mathbb{C}P^n$. Then the complex Laplace operator \square is

(1) positive for on $L^2_{(p,q)}(\Omega)$ with $(n-1) \geq q \geq 1$; and

(2) essentially positive on $L^2_{(p,0)}(\Omega)$ and $L^2_{(p,n)}(\Omega)$

with respect to $\bar{\partial}$ -Neumann boundary condition on $M = b\Omega$.

Moreover, for any Hermitian metric on Ω , the operator \square is essentially positive on Ω with respect to $\bar{\partial}$ -Neumann boundary condition on M .

For the L^2 estimates of \square , the domains Ω in Theorem 1.2 are not necessarily strictly pseudo-convex. However, for estimates of \square_b on the boundary M^{2n-1} of Ω , we need extra assumptions on M^{2n-1} .

The dual of $\bar{\partial}$ -Neumann problem is the so-called $\bar{\partial}$ -Cauchy problem. A (p, q) -form u is said to satisfy the Cauchy boundary condition on $M = b\Omega$ if

$$u(\xi, \dots)|_z = 0$$

for all $\xi \in T_z^{(0,1)}(M)$ and $z \in M$. If a $\bar{\partial}$ -closed form $f \in C_{(p,q+1)}^\infty(\Omega)$ with a compact support in Ω , then one consider to solve $\bar{\partial}u = f$ such that u has a compact support in Ω as well. Solving $\bar{\partial}u = f$ with compact support is related to the $\bar{\partial}$ -extension problem, via the Kohn-Rossi theory. Using the solution to the $\bar{\partial}$ -extension problem and Theorem 1.2, we are able to solve $\bar{\partial}_b u = f$ on a special class of CR-manifolds:

Theorem 1.3. (*[CS], [CaSW]*) *Let Ω be a bounded Hermitian manifold with a smooth pseudo-convex boundary M . Suppose that one of the following conditions holds:*

- (1) *Ω is a domain of a complete Stein manifold V^{2n} ;*
- (2) *$\Omega \subset \mathbb{C}P^n$, and $M = b\Omega$ admits a pluri-subharmonic defining function.*

Then the $\bar{\partial}$ -Cauchy boundary problem is solvable on Ω . Furthermore, (1) $\bar{\partial}_b$ -operator is closed; and (2) the operator $\square_b : L_{(p,q)}^2(M) \rightarrow L_{(p,q)}^2(M)$ is positive for $1 \leq q \leq n-2$ and essentially positive for $q = 0$ or $q = n-1$.

When $M = b\Omega$ is strongly pseudo-convex, it is well-known that M admits a pluri-subharmonic defining function, see [DF].

If $\mathcal{L} : H_1 \rightarrow H_2$ is a linear operator, we let $\text{Dom}(\mathcal{L})$ be its domain and $\mathcal{R}(\mathcal{L})$ be its range. If $A \subset H$ is a subset of a Hilbert space H , the closure of A in H is denoted by \bar{A} .

We begin with an elementary but useful criterion for closed operators.

Lemma 1.4. (*[CS, p60] or [Hö1-2]*) *Let $\mathcal{L} : H_1 \rightarrow H_2$ be a linear, closed, densely*

defined operator from the Hilbert space H_1 to another Hilbert space H_2 . The following conditions on \mathcal{L} are equivalent:

- (1) The range $\mathcal{R}(\mathcal{L})$ of \mathcal{L} is closed;
- (2) There is a constant C such that

$$\|f\|_1 \leq C\|\mathcal{L}f\|_2$$

for all $f \in \text{Dom}(\mathcal{L}) \cap \mathcal{R}(\mathcal{L}^*)$;

- (3) The range $\mathcal{R}(\mathcal{L}^*)$ of \mathcal{L}^* is closed;
- (4) There is a constant C such that

$$\|f\|_2 \leq C\|\mathcal{L}^*f\|_1$$

for all $f \in \text{Dom}(\mathcal{L}^*) \cap \mathcal{R}(\mathcal{L})$.

2. THE EXISTENCE OF CR Q -FLAT METRICS ON STRICTLY PSEUDO-CONVEX CR-HYPERSURFACES IN A STEIN MANIFOLD

In this section, we first recall an existence result of CR Q -flat metrics on CR-hypersurfaces in Euclidean space \mathbb{C}^n due to Fefferman and others. Afterwards, we will extend such a result to CR-hypersurfaces in an arbitrary Stein Manifold V^{2n} . One of our key steps is to use the $\bar{\partial}$ -theory to introduce the generalized Fefferman's functional $u \rightarrow \hat{J}(u)$, which is independent of the choice of local holomorphic coordinates, see (2.5) below.

2.a. A sufficient condition for existence of Q -flat metrics on real hypersurfaces.

Let us recall a sufficient condition for existence of Q -flat metrics on real hypersurfaces, which were derived by Fefferman and others.

Proposition 2.0. ([FG1-2], [GG]) *Let $\Omega \subset \mathbb{C}^n$ be a compact domain with smooth boundary $M^{2n-1} = b\Omega$ in the complex Euclidean space \mathbb{C}^n . Suppose Σ^{2n} is an unit*

circle bundle defined on a CR-hypersurface M^{2n-1} and suppose that Σ^{2n} admits an S^1 -invariant Einstein-Lorentz metric $g_u^+ = i\partial\bar{\partial}H_u|_{\Sigma^{2n}}$ defined as below. Then M^{2n-1} admits a metric of zero CR Q-metric.

We now provide a description of the metric g_u^+ stated in Proposition 2.0, which will be used for any real hypersurface M^{2n-1} in a Stein manifold V^{2n} as well.

Let K^* be the canonical bundle of V^{2n} restrict to M and let $\Sigma^{2n} = K^*/\mathbb{R}^+$ be the unit circle bundle of K^* . Thus there is a fibration

$$S^1 \rightarrow \Sigma^{2n} \rightarrow M^{2n-1}$$

and $\dim_{\mathbb{R}}(\Sigma^{2n}) = 2n$.

We may assume that $\Omega \subset V^{2n}$ is an open strictly pseudo-convex domain with compact smooth boundary $M^{2n-1} = b\Omega$. Suppose that \hat{u} is a defining function of M^{2n-1} . For example, we can choose \hat{u} as a signed distance function from M :

$$\hat{u}(z) = \begin{cases} -d(z, M), & \text{if } z \in \Omega \\ d(z, M), & \text{if } z \notin \Omega \end{cases}$$

Any other defining function u can be expressed as

$$u(z) = e^{\eta} \hat{u}$$

for some real valued function η .

The contact structure on M is an 1-form given by

$$\theta_u(\xi) = du(J\xi)$$

for all $\xi \in [T(M)]_{\mathbb{R}}$, where J is the complex structure of V^{2n} .

There are two types of metrics which we will use. The first one is the Cheng-Yau metric on Ω ; and the second one is introduced by Fefferman on a line bundle over $b\Omega$.

Let us first consider complete Kähler metrics on an open domain Ω . Suppose that

$$\omega_u = i\partial\bar{\partial}[\log(-\frac{1}{u})]$$

is a Kähler form on Ω . Such a Kähler form ω_u corresponds to a Kähler metric

$$g_u(X, Y) = \omega_u(X, JY) = i\partial\bar{\partial}[\log(-\frac{1}{u})](X, JY), \quad (2.1)$$

where J is the complex structure of Ω .

Secondly, Fefferman and his school considered a class of Lorentz metrics on canonical bundle on K^* mentioned above.

We will use an extrinsic way to define such metrics, along the line described in a new book [DT, p150]. Suppose that $\Lambda_{(n,0)}(V^{2n})$ be the canonical line bundle of open domain V^{2n} . Clearly, $\mathcal{L}_{V^{2n}} = \Lambda_{(n,0)}(V^{2n})$ is a complex manifold of complex dimension $(n+1)$.

When ξ is a cross-section of $\mathcal{L}_{V^{2n}}$ over V^{2n} , the norm $|\xi|_{g_u}$ induced by g_u is well-defined. We further define

$$H_u(z, \xi) = |\xi|^{\frac{2}{n+1}}_{g_u} u(z)$$

There is an $(1, 1)$ -form defined on $\mathcal{L}_{V^{2n}}$ given by $i\partial\bar{\partial}H_u$.

Similarly, there is a Hermitian form

$$G_u(\tilde{X}, \tilde{Y}) = i\partial\bar{\partial}H_u(\tilde{X}, \tilde{J}\tilde{Y}), \quad (2.2)$$

where \tilde{J} is the complex structure of line bundle $\mathcal{L}_{V^{2n}}$. The Hermitian form G_u is *not* necessarily positive definite on the complex manifold $\mathcal{L}_{V^{2n}}$.

We now consider a subset

$$\Sigma^{2n} = \{(z, \xi) \in \mathcal{L}_{V^{2n}} \mid z \in b\Omega, |\xi| = 1\} \quad (2.3)$$

where Ω is an open, bounded and strictly pseudo-convex domain in V^{2n} .

Finally, when $i\partial\bar{\partial}u > 0$ on $M = b\Omega$, we consider

$$g_u^+ = G_u|_{\Sigma^{2n}}. \quad (2.4)$$

It was shown that g_u^+ is a Lorentz metric on Σ^{2n} . Clearly, Σ^{2n} is diffeomorphic to the unit circle bundle K^* mentioned above.

We remark that the function $u = 0$ *vanishes* on M^{2n-1} . The leading term of the metric g_u^+ is

$$i\partial\bar{\partial}u.$$

In [FH], Fefferman and Hirachi studied the so-called Q -curvature of CR -manifold M^3 :

$$Q_{\theta_u}^{CR} = \frac{4}{3}(\Delta_b R - 2Im\nabla^\alpha \nabla^\beta A_{\alpha\beta}),$$

where R is the Tanaka-Webster scalar curvature, A is the torsion, Δ_b is the sub-Laplacian computed in terms of the contact 1-form θ_u and $\theta_u(\xi) = du(J\xi)$ for all $\xi \in T(M)$.

For higher dimensional manifolds, the Q -curvatures of higher order have been studied in [FH] and [GG].

The notations above will be used in the next two sub-sections.

2.b. Relations between the Fefferman's Lorentz metric and the Cheng-Yau's Kähler-Einstein metric.

In this sub-section, we illustrate a strategy to obtain the existence of Q -flat metrics on real hypersurfaces in \mathbb{C}^n .

Let us now recall a result obtained by Fefferman and his school.

Proposition 2.1. (*[FG1, Chapter III]*) *Let $\Omega \subset V^{2n}$, $M = b\Omega \subset \mathbb{C}^n$, $u = \hat{u}e^\eta$ and $\{g_u, g_u^+\}$ be as above. If the Cheng-Yau metric g_u is a complete Kähler-Einstein on Ω , then the Lorentz metric g_u^+ is Einstein on Σ^{2n} .*

Here is a direct application of Propositions 2.0-2.1.

Corollary 2.2. (*[FH], [GG]*) *Let $\Omega \subset \mathbb{C}^{2n}$ be an open strictly pseudo-convex domain with compact closure and let $M^{2n-1} = b\Omega$ be its boundary. Then M admits a metric of zero CR Q -curvature.*

Proposition 2.1 and Corollary 2.2 were stated for strictly pseudo-convex and bounded domain Ω in \mathbb{C}^n . We would like to extend these results to any strictly pseudo-convex and bounded domain Ω in a Stein manifold V^{2n} .

2.c. Compact smooth real hypersurfaces in a Stein manifold.

Our goal of this section is to verify the following theorem.

Proposition 2.3. *Let Ω be a bounded, open and strictly pseudo-convex domain with a smooth boundary in a Stein manifold V^{2n} . If the metric g_u above is a complete Kähler-Einstein metric on Ω , then g_u induces a metric \tilde{g}_u^∞ on $M = b\Omega$ with zero CR Q -curvature.*

Proof. Since V^{2n} is Stein, we may assume that $V^{2n} \subset \mathbb{C}^m$ is a complete submanifold of \mathbb{C}^m , for sufficiently large m . Let \hat{g} be induced metric on $\Omega \subset V^{2n} \subset \mathbb{C}^m$. For each local holomorphic coordinate system $\{(z_1, \dots, z_n)\}$ of Ω , the Ricci tensor \hat{Ric} of \hat{g} is given by

$$\hat{Ric} = -i\partial\bar{\partial}\log[\det \hat{g}_{i\bar{j}}].$$

It is clear that \hat{Ric} is well-defined and independent of the choice of local holomorphic coordinate system $\{(z_1, \dots, z_n)\}$. Moreover, \hat{Ric} is a closed $(1, 1)$ -form on Ω . In what follows, we first would like to solve Poincare-Lelong equation $i\partial\bar{\partial}f = \hat{Ric}$.

For this purpose, we recall a theorem of Dolbeault:

$$H^{(1,1)}(\Omega) = H^{(0,1)}(\Omega, \mathcal{O}|_\Omega)$$

where $\mathcal{O}|_\Omega$ is the bundle of holomorphic $(1, 0)$ -forms.

Since Ω is strictly pseudo-convex and bounded domain in a Stein manifold V^{2n} , by a theorem of Andreotti and Vesentini [AV], we have

$$H^{(0,1)}(\Omega, \mathcal{O}|_\Omega) = 0.$$

In fact, Proposition A.4 of [CaWS, p218] is also applicable for $(0, q)$ -forms with values in $\mathcal{O}|_\Omega$. Thus, $H^{(1,1)}(\Omega) = H^{(0,1)}(\Omega, \mathcal{O}|_\Omega) = 0$. Professor Siu also handled similar formula with values in a vector bundle E , although the weighted functions were not discussed there (cf. [Siu, Chapters 2-3]). Hence, the first Chern class $c_1(\mathcal{O}|_\Omega) = 0$. Recall that, by Chern-Weil theory, the co-homology class $c_1(\mathcal{O}|_\Omega)$ is independent of the choices of affine connections, (cf. [Mi]). Therefore, $c_1(\mathcal{O}|_\Omega) = 0$ implies that the Chern-Weil form \hat{Ric} is d -exact on Ω .

Therefore, we have $\hat{Ric} = d\beta$ for some 1-form β . Let us consider the decomposition of $\beta = \beta^{(1,0)} + \beta^{(0,1)}$, where $\beta^{(0,1)}$ is the $(0,1)$ -component of β . If $\hat{Ric} = d\beta$ and if $\beta = \beta^{(0,1)} + \beta^{(1,0)}$, then $\bar{\partial}\beta^{(0,1)} = 0$, where we used the fact that \hat{Ric} is an $(1,1)$ -form. Choosing f with $\bar{\partial}f = i\beta^{(0,1)}$, we get a solution $i\partial\bar{\partial}f = \hat{Ric}$.

Recall that \hat{Ric} is real valued. Replacing f by $Re\{f\}$ if needed, we conclude that the Poincare-Lelong equation

$$i\partial\bar{\partial}f = \hat{Ric} = -i\partial\bar{\partial}\log[\det \hat{g}_{i\bar{j}}].$$

has a smooth real-valued solution f on $\Omega \cup b\Omega$. Such a solution f is unique up to adding a pluri-subharmonic function. If we require that f has the smallest $L^2(\Omega)$ -norm, then such a solution is unique, see Chapters 4-5 of [CS]. Such a solution f is called a Ricci potential of \hat{g} .

Following Fefferman [F2], we consider

$$\hat{J}(u) = (-1)^n e^{-f} \frac{1}{\det \hat{g}_{i\bar{j}}} \det \begin{pmatrix} u & u_{\bar{j}} \\ u_i & u_{i\bar{j}} \end{pmatrix} \quad (2.5)$$

where f is the Ricci potential of \hat{g} as above, $u_i = \frac{\partial u}{\partial z_j}$, $u_{i\bar{j}} = \frac{\partial^2 u}{\partial z_i \partial \bar{z}_j}$ and $\{z_1, \dots, z_n\}$ is a local holomorphic frame.

When $\Omega \subset \mathbb{C}^n$, we choose the standard coordinate system. Thus, in this case, $\det \hat{g}_{i\bar{j}} = 1$ and we can choose $f = 0$. Therefore, our definition coincides with Fefferman's definition for the case of $\Omega \subset \mathbb{C}^n$, see [F2] and [CY].

A calculation similar to [CY, p508] further shows that the metric g_u is Kähler-Einstein of negative curvature $-(n+1)$ if

$$\frac{\det \varphi_{i\bar{j}}}{\det \hat{g}_{i\bar{j}}} = e^f e^{(n+1)\varphi} \quad (2.6)$$

holds, where $\varphi = \log(-\frac{1}{u})$.

A further calculation shows that the above equation holds if and only if

$$\hat{J}(u)|_z \equiv 1 \quad (2.7)$$

holds for all $z \in \Omega$.

It is known that if $\hat{J}(u)|_z \equiv 1$ in Ω , then $M = b\Omega$ has zero CR Q-curvature, see [FH, Chapter 3]. This completes the proof of Proposition 2.3. \square

Corollary 2.4. *Suppose that $\Omega \subset V^{2n}$ be a bounded, open and strictly pseudoconvex domain with smooth boundary in a Stein manifold V^{2n} with $n \geq 2$. Then its boundary $M^{2n-1} = b\Omega$ admits a metric of zero Q-curvature.*

Proof. By Proposition 2.3, it remains to verify that there is a complete Kähler-Einstein metric g_u on Ω . The existence of such a complete Kähler-Einstein metric g_u is provided by Mok-Yau in [MY, p52]. In fact, Mok and Yau found desired solutions $u = e^\eta \hat{u}$ and $\varphi = \log(-\frac{1}{u})$ satisfying $\frac{\det \varphi_{i\bar{j}}}{\det \hat{g}_{i\bar{j}}} = e^f e^{(n+1)\varphi}$. \square

3. EXISTENCE OF PSEUDO-EINSTEIN METRICS ON CR-HYPERSURFACES OF REAL DIMENSION ≥ 5

In this section, we discuss the existence of pseudo-Einstein metrics on CR-hypersurfaces of real dimension ≥ 5 . A metric g defined on a CR-manifold M^{2n-1} is said to be *pseudo-Einstein (or partially Einstein)* if its Ricci tensor satisfies

$$Ric_g(X, Y)|_z = \lambda g(X, Y)|_z \quad (3.0)$$

for some constant $\lambda = \lambda(z)$ and for all real vectors $\{X, Y\}$ in the CR-distribution $\ker(\theta)|_z$, where θ is the contact form of M^{2n-1} .

One of our new contributions in this section is to use the $\bar{\partial}_b$ -theory to solve boundary version of Poincaré-Lelong equation related to the *partially Einstein equation*, see Proposition 3.4 and Corollary 3.5 below.

When $\dim_{\mathbb{R}}[M^{2n-1}] = 3$, any metric g on M^3 is *pseudo-Einstein* (i.e., *partially Einstein*). Therefore, we only consider the case of $\dim_{\mathbb{R}}[M^{2n-1}] \geq 5$.

We emphasize that a pseudo-Einstein metric g on M^{2n-1} is *not* necessarily Einstein. The pseudo-Einstein condition puts *no* restriction on its Ricci curvature in the directions which are transversal to CR -distribution. It might happen that

$$\text{Ric}_g(Z, Y) \neq \lambda g(Z, Y)$$

for some transversal vector $Z \perp \ker(\theta)$.

In [L2], Lee already showed that, if a compact strongly pseudo-convex CR-manifold M^{2n-1} admits a closed, nowhere vanishing $(n, 0)$ -form, then M^{2n-1} admits a pseudo-Einstein metric. In particular, if $M = b\Omega$ and $\Omega \subset \mathbb{C}^n$, then M admits a pseudo-Einstein structure.

We make extra observations to extend Lee's result to the case of $\Omega \subset V^{2n}$ for any Stein manifold V^{2n} . The new ingredient of our approach will use the fact that the Chern curvature forms Θ are type of $(1, 1)$ for Lorentz-Kähler metrics.

In addition, we will use Kohn's $\bar{\partial}_b$ -theory to solve the boundary version of Poincare-Lelong equation

$$i\partial_b\bar{\partial}_b f = \Theta \tag{3.1}$$

for any $\bar{\partial}_b$ -closed $(1, 1)$ -form Θ .

The equation (3.1) above is related to the existence of pseudo-Einstein metrics, as described in [L2, p173]. Such an equation was previously studied in [CaWS] for other purposes.

It is well-known that, for any function u , one has

$$(d^c u)(\xi) = (du)(J\xi) \text{ and } dd^c u = i\partial\bar{\partial}u.$$

We begin with an elementary observation.

Lemma 3.1. *Let \hat{u} be a defining function of $M = b\Omega$. Suppose that $\Omega \subset V^{2n}$ is a strictly pseudoconvex bounded domain in a Stein manifold. Then*

(1) *There is another defining function $u = e^\varphi \hat{u}$ such that u is a strictly pluri-subharmonic in a neighborhood of $M = b\Omega$, i.e., $i\partial\bar{\partial}u > 0$.*

(2) *When $i\partial\bar{\partial}u > 0$ and $\theta_u = d^c u$, then $i\partial\bar{\partial}u$ gives rise to a Kähler metric g_u in a neighborhood of M .*

(3) *If $u = e^\varphi \hat{u}$, $\theta = d^c u$ and $\hat{\theta} = d^c \hat{u}$, then one has*

$$\theta = e^\varphi \hat{\theta} \text{ on } M.$$

Proof. Assertion (1) was stated in Theorem 3.4.4 of [CS, p45-46].

The verification of Assertions (2)-(3) is straightforward. \square

Proposition 3.2. *Let Ω be a bounded, strictly pseudo-convex domain with a smooth boundary $M = b\Omega$ in a Stein manifold V^{2n} , let \mathcal{O} be the holomorphic $(1,0)$ -form bundle of V^{2n} , and let K^* be the canonical line bundle of V^{2n} . Suppose that $\dim_{\mathbb{R}}[V^{2n}] = 2n \geq 6$. Then the following is true.*

(1) *The first Chern class of $\mathcal{O}|_{\Omega}$ is equal to zero, i.e., $c_1(\mathcal{O}|_{\Omega}) = 0$; Moreover, the first Chern class of canonical line $c_1(K^*|_M) = 0$;*

(2) *The Ricci curvature form Ric_g of any metric $g = d\theta$ on $\mathcal{O}|_{\Omega}$ is a d -exact $(1,1)$ -form on M . Furthermore, $\text{Ric}(\xi, \bar{\xi})$ is a real number for all $\xi \in T^{(1,0)}(M)$.*

Proof. (1) We will use curved version of Kohn-Morrey formula to verify that

$$c_1(\mathcal{O}|_{\Omega}) = 0. \tag{3.2}$$

Recall that the closure $\bar{\Omega}$ of Ω is compact. Since V^{2n} is a Stein manifold, there is a strictly pluri-subharmonic function ϕ_0 . Let $\phi = \lambda\phi_0$ for sufficiently large $\lambda > 0$. Using Bochner-Hörmander-Kohn-Morrey formula, we obtain

$$H^{(p,q)}(\Omega) = 0, \tag{3.3}$$

for all $0 < q < n$, (cf. Proposition A.4 of [CaWS, p218]).

It is well-known that, for $\dim_{\mathbb{C}}(\Omega) = n > 2$

$$H^1(\Omega, \mathcal{O}|_{\Omega}) = H^{(1,1)}(\Omega) = 0. \quad (3.4)$$

It follows that the first Chern class of $\mathcal{O}|_{\Omega}$ is zero.

Choose a Kähler metric \hat{g} on Ω . Then the Ricci curvature form $\hat{\Theta}$ is a d -exact $(1, 1)$ -form.

The classical Kohn-Rossi theory states that any $\bar{\partial}_b$ -closed $(1, 0)$ -form on $M = b\Omega$ can be extend to a unique holomorphic $(1, 0)$ -form on the whole Ω . Thus,

$$H^{(1,1)}(M) = 0, \quad (3.5)$$

see [KoR].

It is also known that $c_1(\mathcal{O}|_M) = c_1(K^*|_M) = 0$.

(2) Let g_u be the Kähler metric associated with the Kähler form $i\partial\bar{\partial}u$. The corresponding first Chern curvature form Θ_u of the Kähler metric g_u is a closed $(1, 1)$ -form in a neighborhood of M in V^{2n} .

The classical Chern-Weil theory implies that the cohomology class of the first Chern curvature form $\Theta|_M$ is independent of the choice of the choice of affine connections on M .

In fact, if $\theta_u = d^c u$ and $i\partial\bar{\partial}u > 0$, then $d\theta_u = dd^c u = i\partial\bar{\partial}u > 0$ gives rise a Kähler metric in a neighborhood of M . For any other $\tilde{\theta} = e^{2\varphi}\theta$, the Ricci curvature form corresponding to $\tilde{\theta}$ remains to be of type $(1, 1)$, see Lemma 2.4 of [L2]. \square

We now recall that a result of Lee [L2].

Proposition 3.3. (*[L2, Lemma 6.1, p173-174]*) *Let $M = b\Omega$ and $\Omega \subset V^{2n}$ be as in Main Theorem. Suppose that $\tilde{\theta} = e^{2u}\hat{\theta}$ and \hat{Ric} is the Ricci curvature form corresponding to $\hat{\theta}$. Then $\tilde{\theta}$ is pseudo-Einstein if and only if there is a real solution u satisfying*

$$i\partial_b\bar{\partial}_b u = \hat{Ric}$$

Proof. By (6.3) of [L2], the trace-less part of \tilde{Ric} is zero if there is φ satisfying

$$(n+1)i\partial_b\bar{\partial}_b\varphi = \hat{Ric}$$

Since \hat{Ric} is a real valued d -exact real-valued $(1,1)$ -form by Proposition 3.2 above, we can choose φ to be real-values as well. (Otherwise, let $v = \frac{1}{2}(\varphi + \bar{\varphi})$ instead). \square

Proposition 3.4. *Let $M = b\Omega$ and $\Omega \subset V^{2n}$ be as in Main Theorem. Suppose that the Ricci curvature form \hat{Ric} form is a d -exact $(1,1)$ -form for the contact 1-form $\hat{\theta}$. Then there always a real-valued function u satisfying*

$$i\partial_b\bar{\partial}_bu = \hat{Ric} \quad (3.6)$$

Proof. Choose σ such that

$$d\sigma = \hat{Ric}. \quad (3.7)$$

Let $\sigma = \sigma^{(0,1)} + \sigma^{(1,0)} + \lambda\theta$, where $\sigma^{(0,1)}$ is $(0,1)$ -component of σ . Since \hat{Ric} is of type $(1,1)$, by (3.7) we have

$$\bar{\partial}_b\sigma^{(0,1)} = 0. \quad (3.8)$$

Because $\dim_{\mathbb{C}}(\Omega) > 2$, by a Theorem of Kohn that there is complex-valued function f with

$$i\bar{\partial}_bf = \sigma^{(0,1)}, \quad (3.9)$$

see [CS, Ch9].

It follows that

$$i\partial_b\bar{\partial}_bf = \partial\sigma^{(0,1)} = (d\sigma)_b = (\hat{Ric})_b. \quad (3.10)$$

Since $(\hat{Ric})_b$ is real-valued $(1,1)$ -form, choosing $u = \text{Re}\{f\}$, we are done. \square

We now summarize our result of this section.

Corollary 3.5. *Suppose that $\Omega \subset V^{2n}$ be a compact strictly pseudo-convex domain with smooth boundary in a Stein manifold V^{2n} . Then its boundary $M^{2n-1} = b\Omega$ admits an intrinsic pseudo-Einstein (i.e., partially Einstein) metric.*

Proof. This is a direct consequence of Lemma 3.1 and Propositions 3.2-3.4. \square

4. ESTIMATES FOR CR PANEITZ OPERATORS ON M^3

In the remaining of this paper, we study the so-called CR Paneitz operator

$$P_u f = \Delta_b^2 f + T^2 f + 4Im \nabla_\beta (A^{\alpha\beta} \nabla_\alpha f), \quad (4.1)$$

where $T = J\nabla u$ is the Reeb vector and A is the torsion tensor of the contact form θ_u .

When the torsion A vanishes, the formula (4.1) reduces to (1.2).

It remains to verify that CR Paneitz operator P_u is a closed operator.

If $\hat{\theta} = e^\varphi \theta_u$ on M^3 and \hat{Q} is the corresponding CR Q -curvature of the metric associated with the contact form $\hat{\theta}$, then

$$e^{2\varphi} \hat{Q} = Q + P_u \varphi,$$

see (5.14) of [GG].

Our goal is to show the following result.

Proposition 4.1. *Let $\Omega \subset V^4$ be an open strictly pseudo-convex domain with compact closure in a Stein manifold V^4 and let $M^3 = b\Omega$ be its boundary. Suppose that g_u is the Cheng-Yau Einstein metric on Ω and $\theta_u(\cdot) = du(J\cdot)$ is the corresponding contact 1-form on M^3 . Then the Paneitz operator P_u is closed:*

$$\int_{M^3} |P_u f|^2 \geq c \int_{M^3} |f|^2, \quad (4.2)$$

for any real valued function $f \perp \ker P_u$, where $c > 0$ is a constant independent of f .

Remark 4.2: The constant c in Proposition 4.1 depends mostly on the Tanaka-Webster curvature R and pseudo-hermitian torsion A_{11} of (M^3, J, θ_u) respectively. In fact, the following holds:

$$\int_M 2(Pf)f\theta_u \wedge d\theta_u = \int_M [3(\Delta_b f)^2 - |Hess_b f|^2 - R|\nabla_b f|^2 - 6Im\{A_{\bar{1}\bar{1}}f_1 f_1\}]\theta_u \wedge d\theta_u$$

where ∇_b and $Hess_b^2$ denotes the sub-gradient and sub-Hessian with respect to (J, θ_u) respectively, see [CC].

For the proof of Proposition 4.1, we need some notations.

In what follows, we let $\theta = \theta_u$ be the given contact form. The vector T is the characteristic vector in $T(M)$ such that $\theta(T) = 1$, $(d\theta)(T, \cdot) = 0$.

An $(1, 0)$ -form $\theta^1 \in \Lambda_{(1,0)}(M^3)$ is called *admissible* if

$$\theta^1(T) = 0, d\theta = ih_{1,\bar{1}}\theta^1 \wedge \theta^{\bar{1}}$$

for some hermitian metric function $h_{1,\bar{1}}$.

It is known that

$$\Delta_b f = -f_\alpha^\alpha - f_{\bar{\alpha}}^{\bar{\alpha}}$$

and

$$\square_b f = 2(\bar{\partial}_b^* \bar{\partial}_b + \bar{\partial}_b \bar{\partial}_b^*) f = (\Delta_b + iT)f = -2f_{\bar{\alpha}}^{\bar{\alpha}}.$$

Inspired by proof of Proposition 3.4 of [L2], we will express the CR Paneitz operator P as a product of several closed operators.

We first consider

$$\mathcal{L}f = d_b^c f + (\Delta_b f)\theta, \tag{4.3}$$

where θ is the contact 1-form described above.

Lemma 4.2. *Let $M^3 = b\Omega$, θ , A and \mathcal{L} be as above. Suppose that $\Omega \subset V^4$ is a strictly pseudo-convex domain in a Stein manifold V^4 and that Ω has compact closure. Then \mathcal{L} is a closed operator.*

Moreover, one has

$$d[\mathcal{L}f] = 2(f_{\bar{1}}^{\bar{1}} + iA_{1\bar{1}}f^1)\theta \wedge \theta^1 + 2(f_1^1 - iA_{\bar{1}\bar{1}}f^{\bar{1}})\theta \wedge \theta^{\bar{1}}.$$

Proof. By Theorem 9.4.2 of [CS], both d_b^c and Δ_b are closed operators for strictly pseudo-convex compact CR-hypersurfaces. Notice that $d_b^c f \in [\Lambda_{(1,0)}(M^3) \oplus \Lambda_{(0,1)}(M^3)]$ is always orthogonal to the 1-form $(\Delta_b f)\theta$. Hence, \mathcal{L} is a closed operator.

We will use the proof of Proposition 3.4 of [L2].

The $\theta^1 \wedge \theta^{\bar{1}}$ -component of $d[\mathcal{L}f]$ is

$$i[f_{1\bar{1}} + f_{\bar{1}1} - (f_1^1 + f_{\bar{1}}^{\bar{1}})h_{1\bar{1}}]\theta^1 \wedge \theta^{\bar{1}} = 0.$$

On the other hand, the $\theta \wedge \theta^1$ -component of $d[\mathcal{L}f]$ is

$$[f_1^1{}_{\bar{1}} + f_{\bar{1}}^{\bar{1}}{}_{\bar{1}} - if_{1,0} + iA_{1\bar{1}}f^1]\theta \wedge \theta^1. \quad (4.4)$$

It is known (cf. [L2, Section 2]) that

$$-f_1^1{}_{\bar{1}} + f_{\bar{1}}^{\bar{1}}{}_{\bar{1}} + if_{1,0} + iA_{1\bar{1}}f^1 = 0. \quad (4.5)$$

It follows from (4.4) and (4.5) that the $\theta \wedge \theta^1$ -component of $d[\mathcal{L}f]$ is equal to

$$2(f_{\bar{1}}^{\bar{1}}{}_{\bar{1}} + iA_{1\bar{1}}f^1)\theta \wedge \theta^1. \quad (4.6)$$

For the same reason, the $\theta \wedge \theta^{\bar{1}}$ -component of $d[\mathcal{L}f]$ is equal to

$$2(f_1^1{}_{\bar{1}} - iA_{\bar{1}\bar{1}}f^{\bar{1}})\theta \wedge \theta^{\bar{1}}. \quad (4.7)$$

This completes the proof. \square

Proof of Proposition 4.1. We now consider the composition of operators:

$$\tilde{P}f = \partial_b^*[(d(\mathcal{L}f))|_T]. \quad (4.8)$$

It follows from that

$$(d(Lf))|_T = 2(f_{\bar{1}}^{\bar{1}}{}_{\bar{1}} + iA_{1\bar{1}}f^1)\theta^1 + 2(f_1^1{}_{\bar{1}} - iA_{\bar{1}\bar{1}}f^{\bar{1}})\theta^{\bar{1}}. \quad (4.9)$$

We observe that ∂_b^* acts on $\Lambda_{(1,0)}(M^3)$ trivially. For real valued function f , we further consider

$$Re[\tilde{P} \circ f] = Re[\bar{\square}_b \square_b f] + 4Im(A_{\bar{1}\bar{1}}f_1)_1, \quad (4.10)$$

where $Re\{z\}$ is the real part of complex number of z .

Therefore, it follows from (4.8)-(4.10) that, for real valued function f , we have

$$Re[\tilde{P}f] = \Delta_b^2 f + T^2 f + 4Im(A_{1\bar{1}}f_1)_1 = Pf. \quad (4.11)$$

Thus, the CR Paneitz operator P satisfies

$$Pf = Re[\tilde{P}f], \quad (4.12)$$

where

$$\tilde{P} = \partial_b^*[(d(\mathcal{L}f))|_T].$$

A composition of closed operators remains to be a closed operator.

If $M^3 = b\Omega$ is a compact strictly pseudo-convex hypersurface in a Stein manifold V^4 , then $\{\bar{\partial}_b, d, \partial_b^*, \mathcal{L}\}$ are closed operators, by Kohn's $\bar{\partial}_b$ -theory (cf. [CS, Theorem 9.4.2, p231]). Theorem 9.4.2 of [CS] was stated for $\Omega \subset \mathbb{C}^2$, but its proof is applicable to Ω in all Stein manifolds V^4 including \mathbb{C}^2 . It is clear that the operator Re is a closed operator. Therefore, $P = Re\tilde{P}$ is a closed operator as well. \square

Proof of Main Theorem. Main Theorem now follows from Corollary 2.4, Corollary 3.5 and Proposition 4.1. \square

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